L Number	Hits	Search Text	DB	Time stamp
30	229	motion near detect$3 same sensors! and forward and reverse	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 14:35
31	118	motion near detect$3 same sensors! and forward same reverse	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 14:35
35	2	6272443.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 15:01
36	2	three near sensors! same direction same object with (movement motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 15:03
37	29	three near sensors! same direction same object and (movement motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 15:04
38	108	three near sensors! same direction and object with (move$5 motion)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 15:05
39	13	three near sensors! same direction and object with (move$5 motion) and forward and reverse	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 15:05
-	21	sensor same signal same process same speed same direction same position same size	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:15
-	24	sensor same signal same process and speed same direction same position same size and object with motion	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/20 13:28
-	108	object with motion and sensor with signal and ris$3 same fall$3 same edge	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/20 13:29
-	107	object with motion and sensor with signal and ris$3 same fall$3 same edge and (position speed direction size)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/20 13:30
-	50	object with motion and sensor with signal and ris$3 same fall$3 same edge and (position and speed and direction and size)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/20 14:33
-	28	object with motion and sensor with signal and ris$3 same fall$3 same edge and (position and velocity and direction and size)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/20 14:46
-	37	object with motion and sensor with signal and ris$3 same fall$3 same edge and (position and velocity and direction)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/20 14:46
-	259	ris$3 same fall$3 same edge and sensors! and object same (motion movement)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:16
-	221	ris$3 same fall$3 same edge and sensors! and object with (motion movement)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:16
-	30	ris$3 same fall$3 same edge and sensors! same object with (motion movement)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:27

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-	16	ris$3 same fall$3 same edge and sensors! same object with (motion movement) and size	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:28
-	1761	sensors! same size same object	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:28
-	494	sensors! with size with object	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:29
-	4	sensors! with size with object and ris$3 same fall$3 same edge	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 13:30
-	142	sensors! with size with object with (determin$3 measur$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 14:57
-	243	distance with between with sensors with (cm centimeters)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 15:26
-	3	distance with between with sensors with (cm centimeters) with adjacent	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 15:22
-	26	distance with between with sensors with (cm centimeters) and object same (motion movement)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 15:24
-	66	distance with between with sensors! with (cm centimeters)	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 15:26
-	5290	(speed velocity) and direction and position and sensors and forward and reverse and (mov$5 motion) with object	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 17:10
-	321	(speed velocity) same direction same position same sensors and forward same reverse and (mov$5 motion) with object	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/21 17:11
-	83	(speed velocity) same direction same position same sensors and forward same reverse and (mov$5 motion) with object same sensors	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/09/22 14:27

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